## Eigen-feature Analysis of Weighted Covariance Matrices for LiDAR Point Cloud Classification

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#### Part A: Visual Comparisons

- -- Eigen-features from the proposed method
- -- Eigen-featurs from the standard method

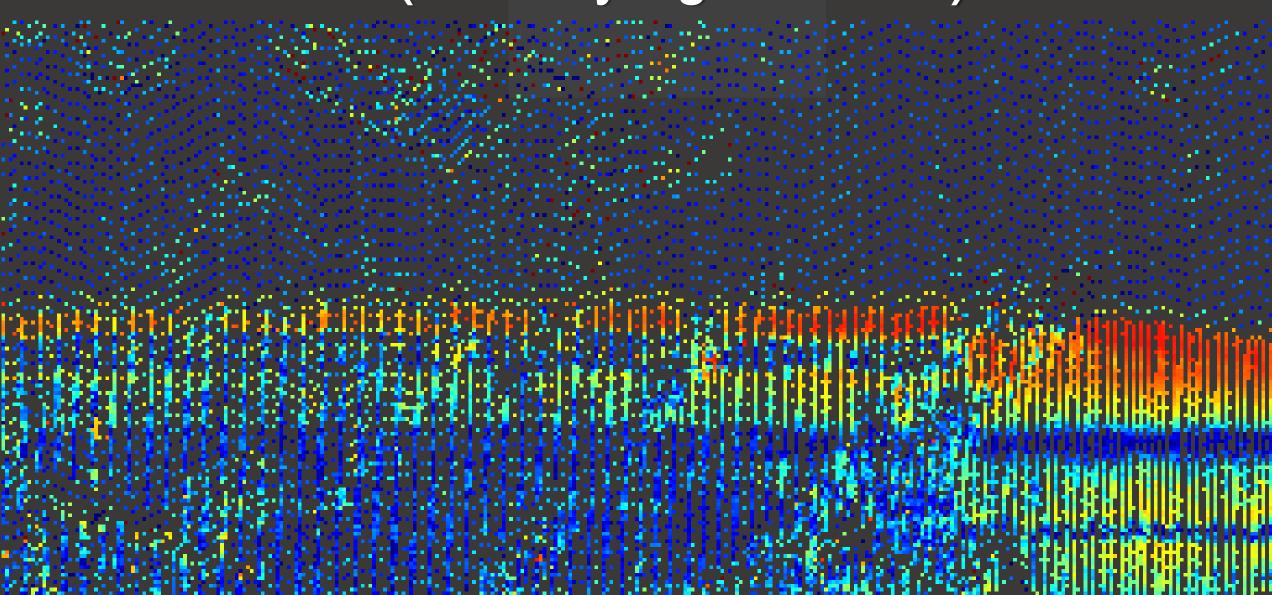




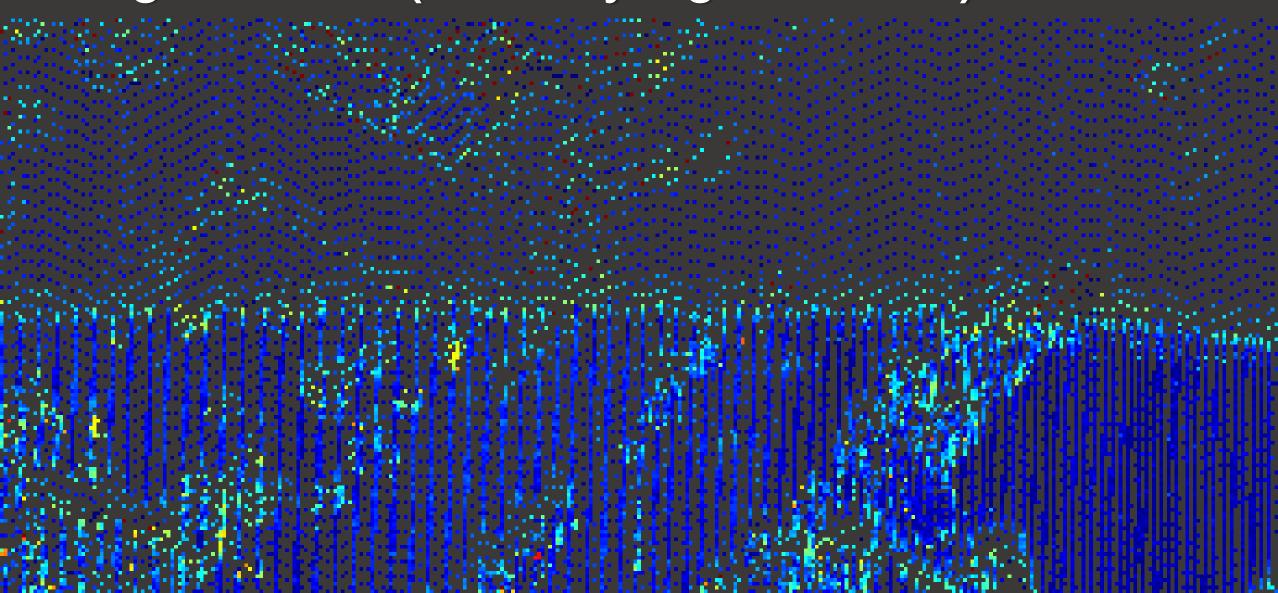
## Standard PCA (linearility eigen-feature) Un-overlapping region A. Strip boundary B. Building Overlapping region

## Weighted PCA (linearility eigen-feature) Un-overlapping region A. Strip boundary B. Building Overlapping region

#### A. Strip boundary Standard PCA (linearility eigen-feature)



### A. Strip boundary Weighted PCA (linearility eigen-feature)



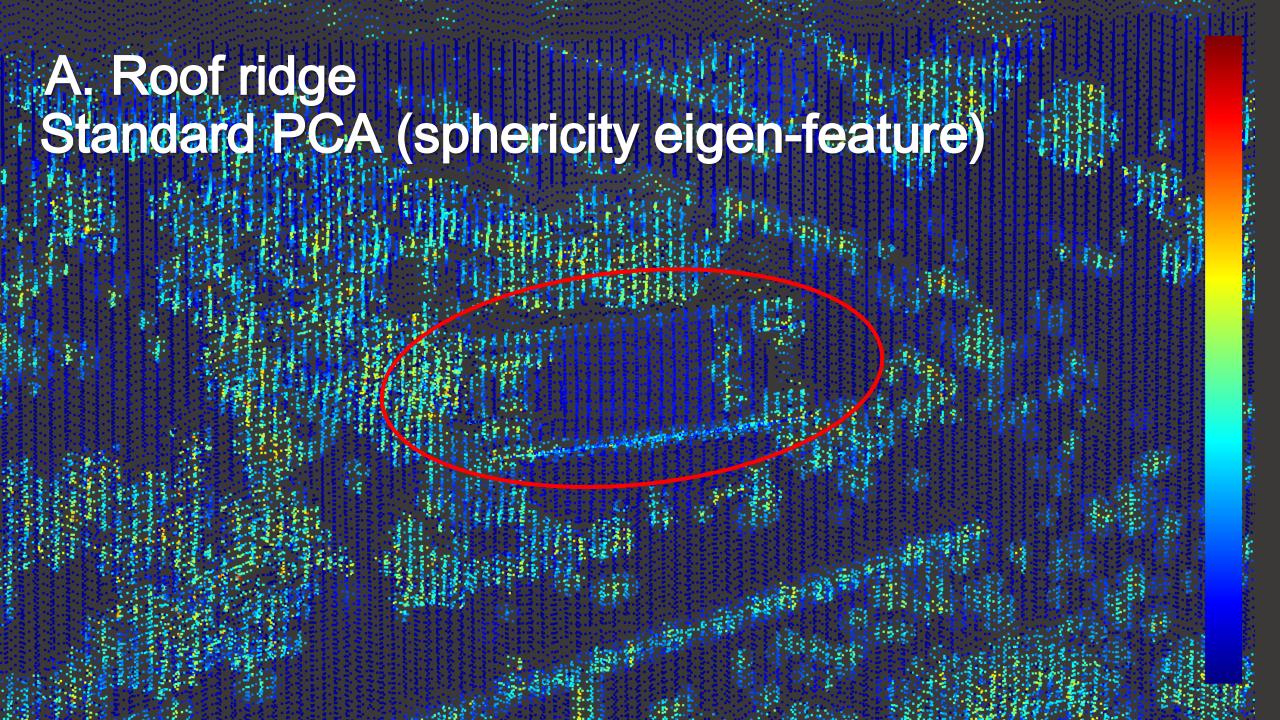
# nearility eigen-feat Building Standard PCA

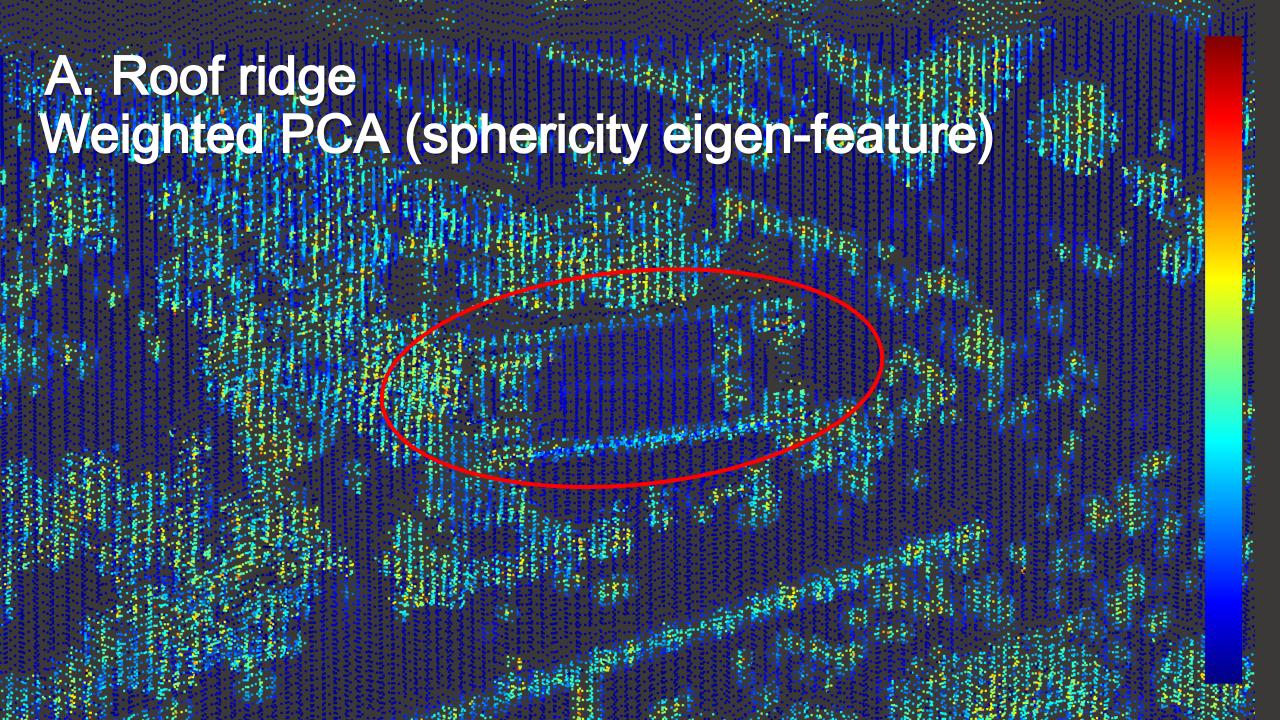
# (linearility eigen-feature) B. Building Weighted PCA

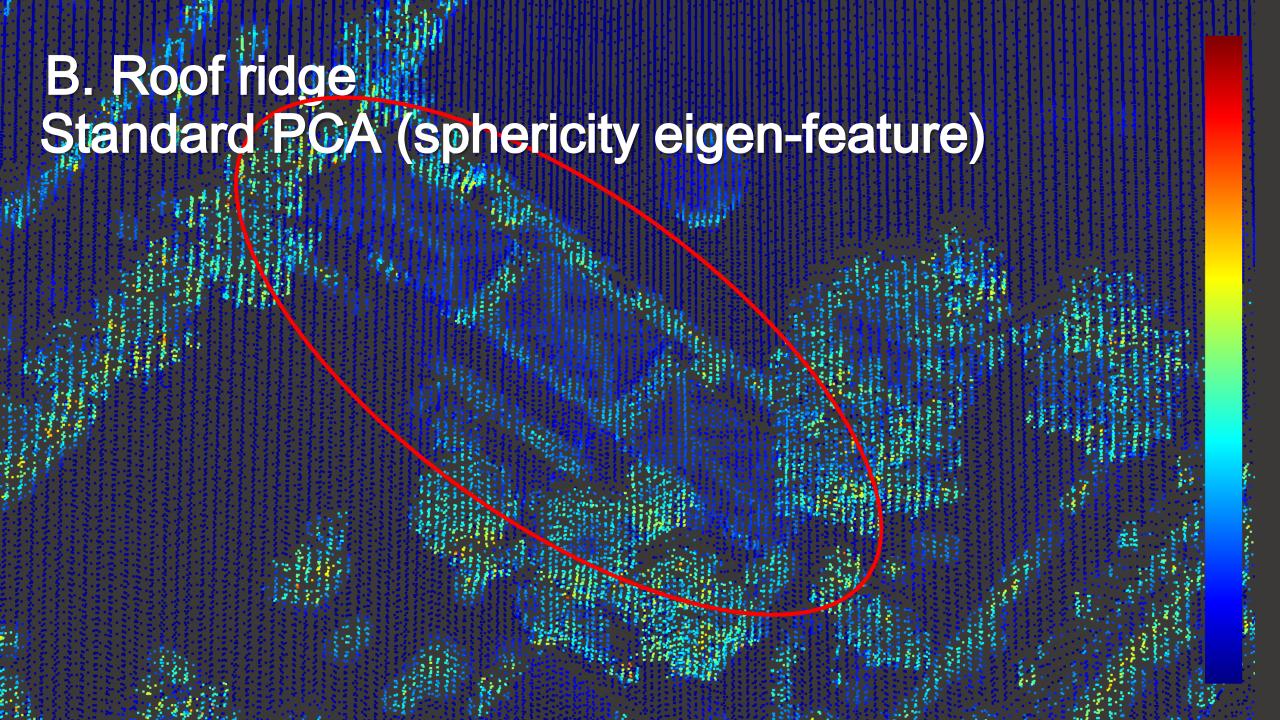


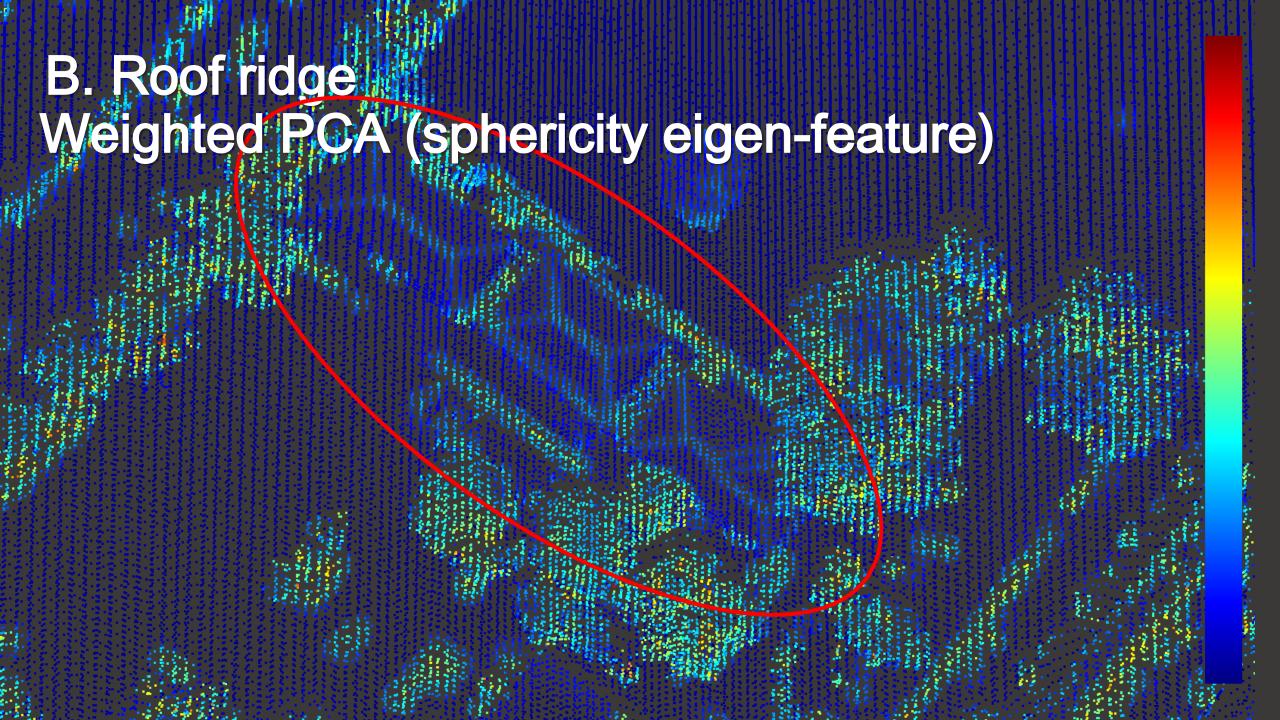
### Standard PCA (sphericity eigen-feature) C. Strip boundary Un-overlapping region A. Roof ridge B. Roof ridge Overlapping region

## Weighted PCA (sphericity eigen-feature) C. Strip boundary A. Roof ridge B. Roof ridge

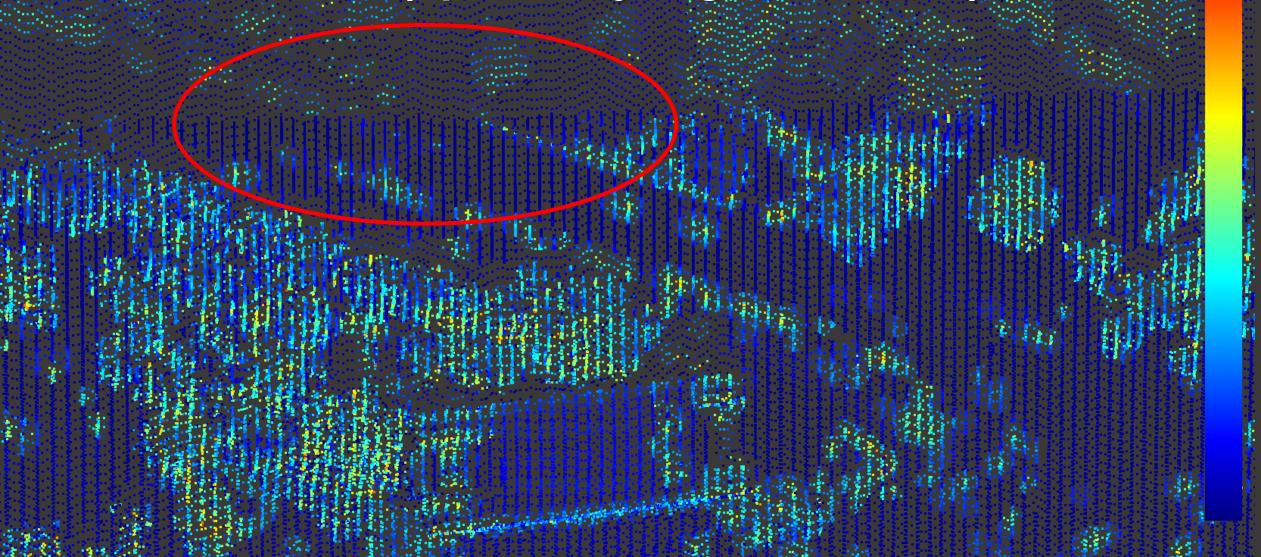




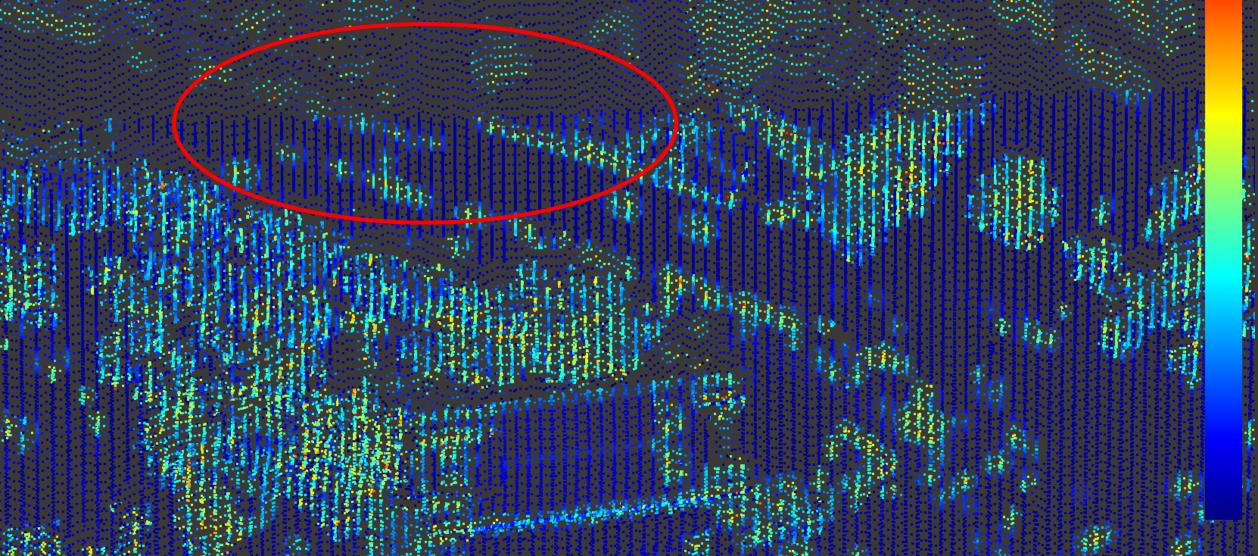




## C. Strip Standard PCA (sphericity eigen-feature)



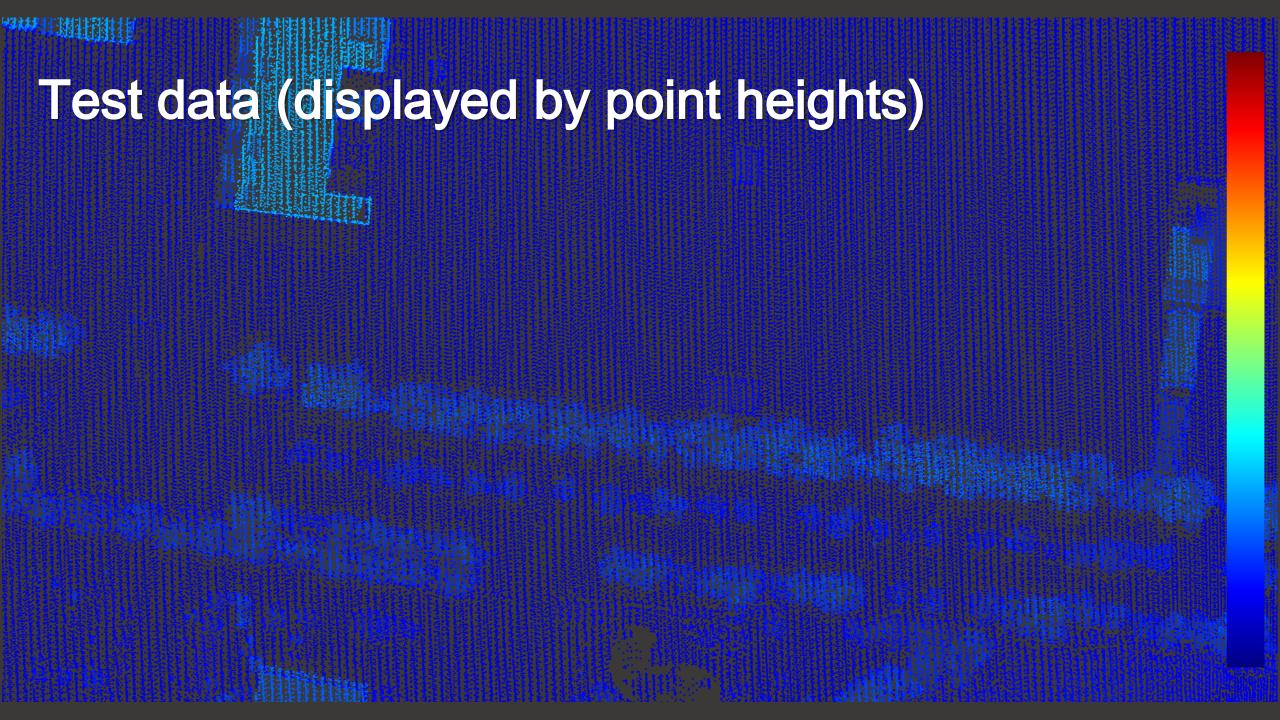
## C. Strip boundary Weighted PCA (sphericity eigen-feature)



#### Part B: Visual Comparisons

-- Point cloud classification using eigen-features





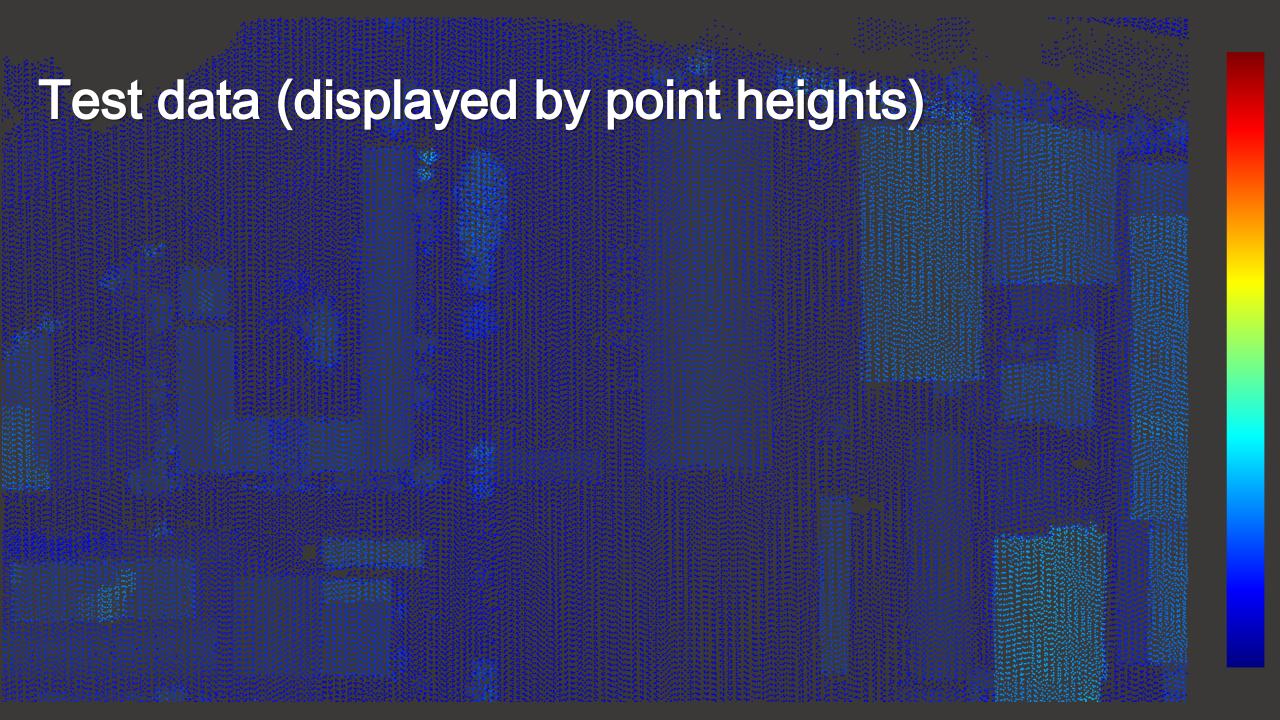
#### Standard PCA

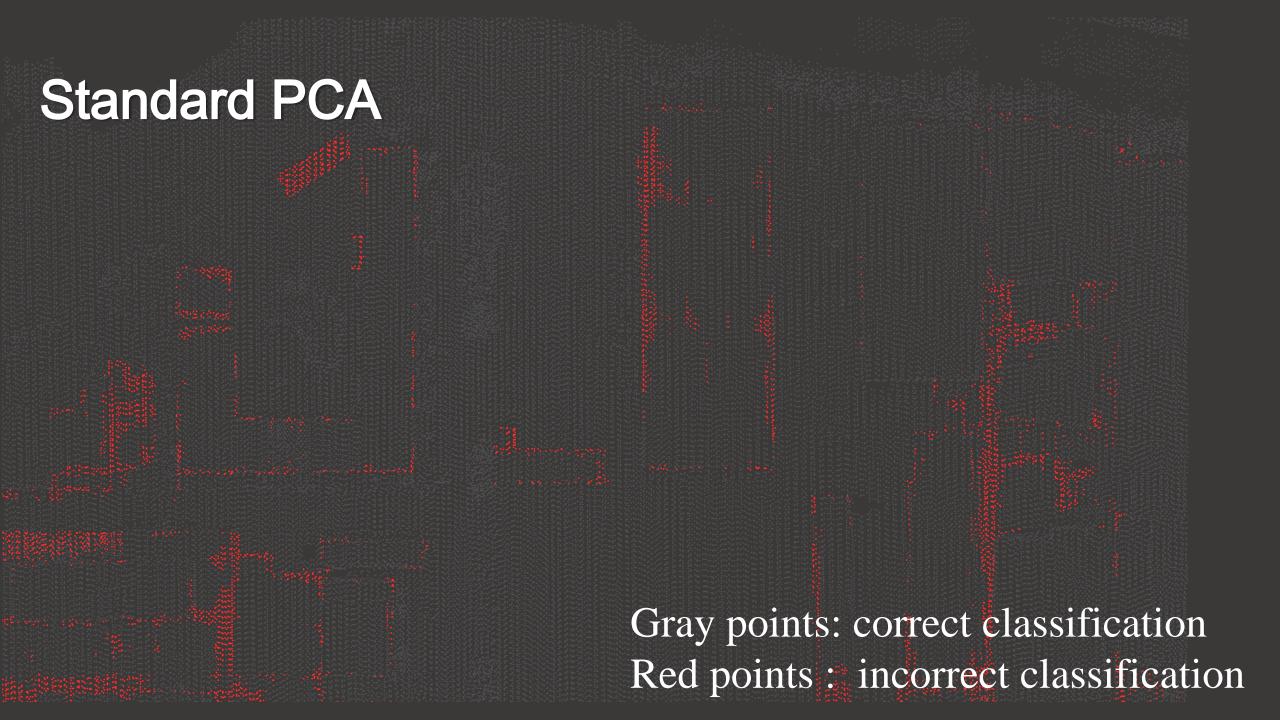
Gray points: correct classification Red points: incorrect classification

#### Weighted PCA

Gray points: correct classification Red points: incorrect classification







## Weighted PCA Gray points: correct classification Red points: incorrect classification